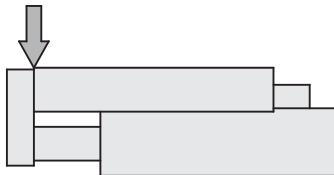


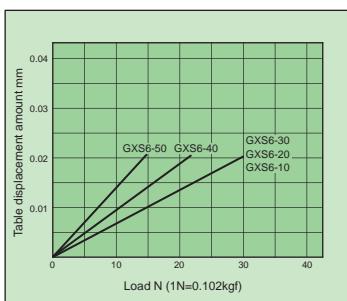
## Table deflection

### Table deflection by pitch moment

Table pitch deflection owing to static pitch moment applied at arrow for fully extended stroke of slide table

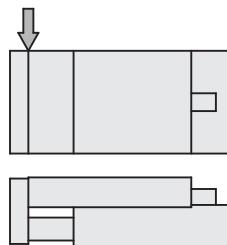


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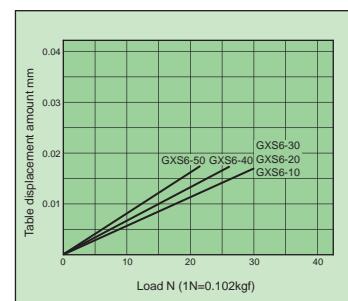


### Table deflection by yaw moment

Table yaw deflection owing to static yaw moment applied at arrow for fully extended stroke of slide table.

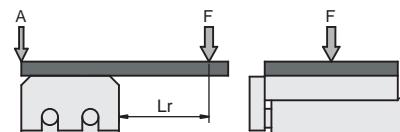


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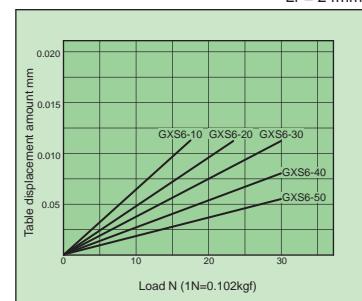


### Table deflection by roll moment

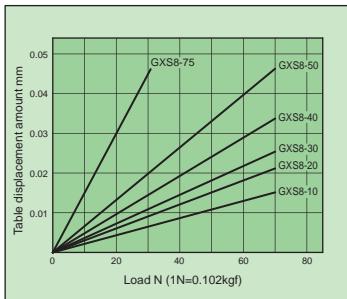
Table roll deflection arrow A owing to static roll moment applied at arrow F when  $L_r =$ (see table) and table is retracted.



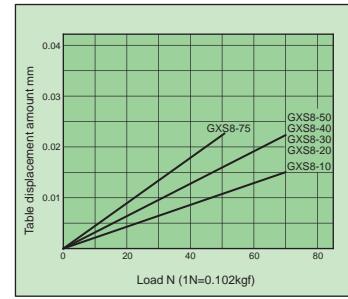
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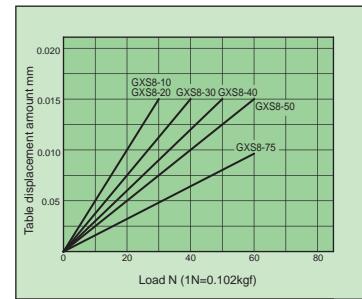
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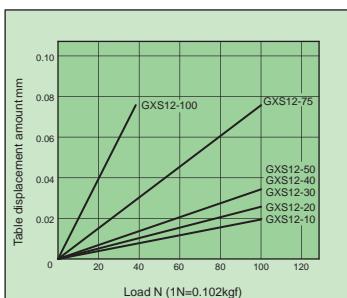
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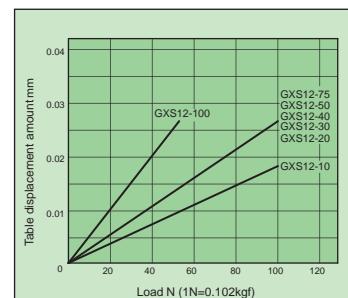
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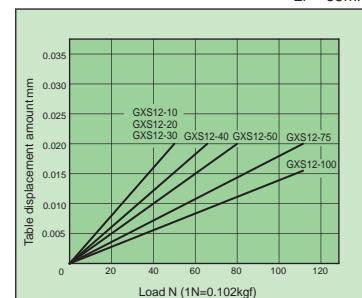
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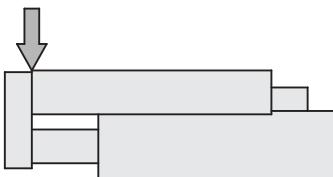
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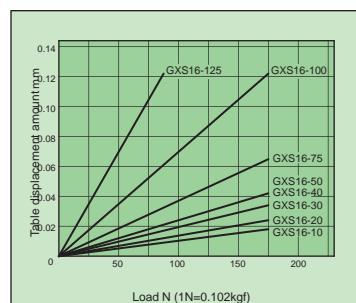
## Table deflection

### Table deflection by pitch moment

Table pitch deflection owing to static pitch moment applied at arrow for fully extended stroke of slide table

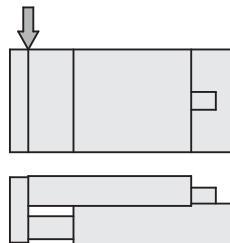


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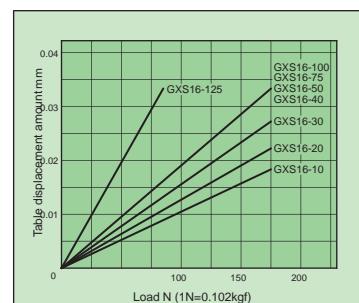


### Table deflection by yaw moment

Table yaw deflection owing to static yaw moment applied at arrow for fully extended stroke of slide table.

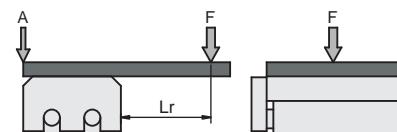


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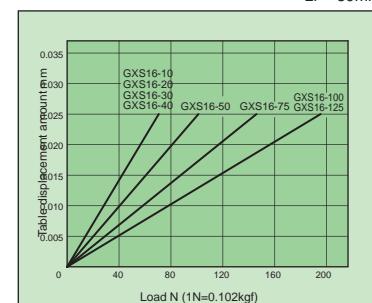


### Table deflection by roll moment

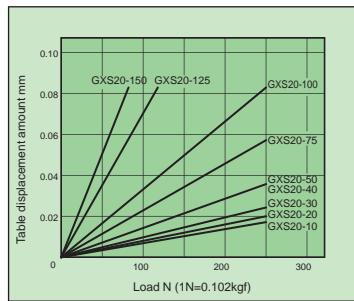
Table roll deflection arrow A owing to static roll moment applied at arrow F when  $L_r$ =(see table) and table is retracted.



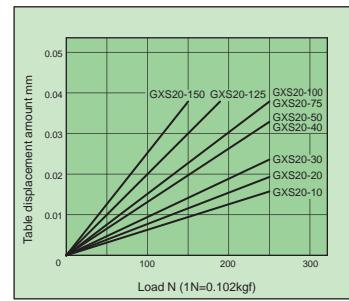
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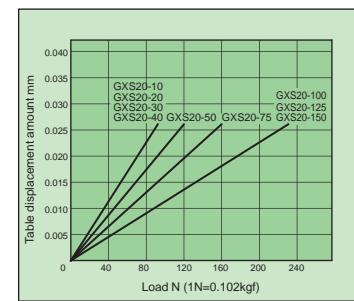
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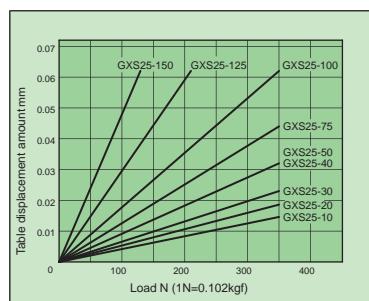
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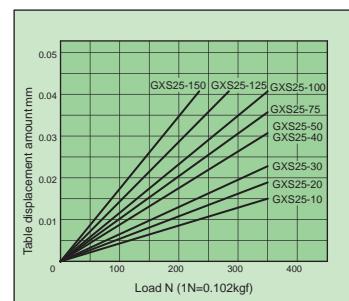
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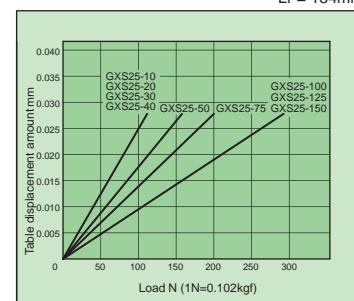
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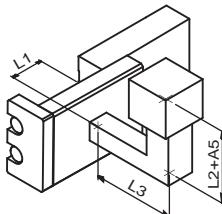
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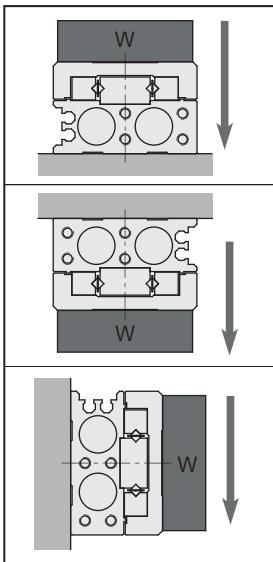
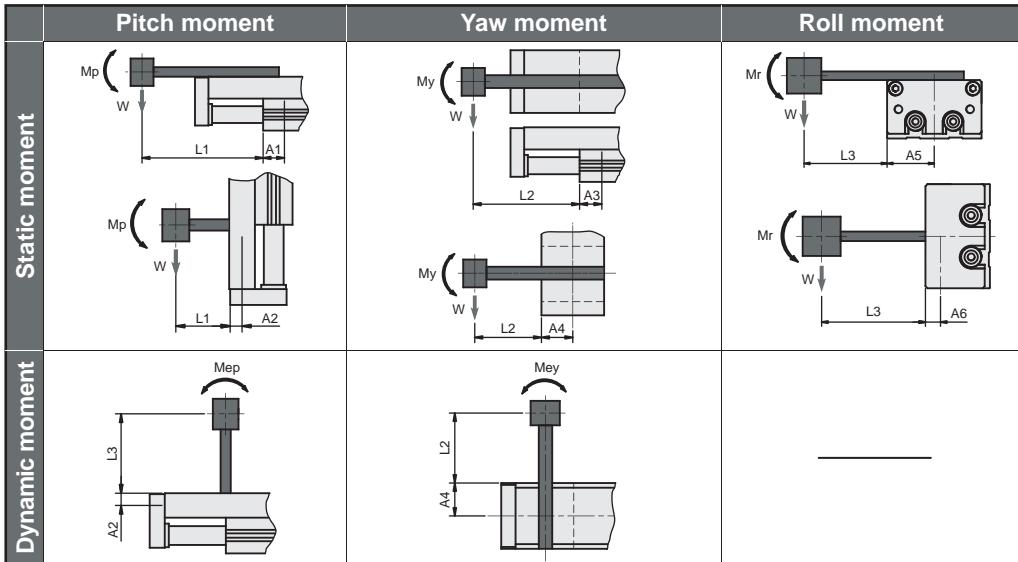
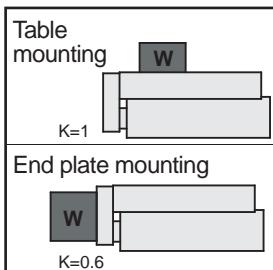


**Ø25**



### How to select

Model Selection Steps	Formula and Data	Selection Examples
<b>Operating Conditions</b>		
1 List the operating conditions considering the mounting position and workpiece configuration.	<ul style="list-style-type: none"> <li>● Model to be used</li> <li>● Type of cushion</li> <li>● Mounting position of workpiece</li> <li>● Mounting direction</li> <li>● Average speed <math>V_a</math> (mm/s)</li> <li>● Load mass <math>W</math> (kg) : Fig.1</li> <li>● Overhang <math>L_n</math> (mm) : Fig.2</li> </ul>	 <p>Cylinder : GXS16X50  Cushion : Rubber cushion  Work table mounting  Mounting : Horizontal  Average speed: <math>V_a = 300(\text{mm/s})</math>  Load <math>W = 1(\text{kg})</math>  <math>L_1 = 10\text{mm}</math>  <math>L_2 = 30\text{mm}</math>  <math>L_3 = 30\text{mm}</math></p>
<b>Kinetic Energy</b>		
2 Calculate kinetic energy $E$ (J) of work.  Calculate allowable kinetic energy $E_a$ (J).  Make sure that kinetic energy of work does not exceed allowable kinetic energy.	$E = \frac{1}{2} \cdot \frac{w}{9.8} \left( \frac{V}{1000} \right)^2$ <p>Collision speed <math>V = 1.4 \cdot V_a</math>  <math>E_a = K \cdot E_{\max}</math>      *Corrected coefficient  Workpiece mounting coefficient <math>K</math> : Fig.3  Max. allowable kinetic energy <math>E_{\max}</math> : Table 1  Kinetic energy (<math>E</math>) ≤ Allowable kinetic energy (<math>E_a</math>)</p>	$E = \frac{1}{2} \cdot 1 \left( \frac{420}{1000} \right)^2 = 0.088$ $V = 1.4 \times 300 = 420$ $E_a = 1 \cdot 0.11 = 0.11$ <p>Possible to use by <math>E=0.088 \leq E_a=0.11</math></p>
<b>Load Rate</b>		
<b>3-1 Load rate of work</b>	Calculate static work $W_a$ (kg)  $W_a = K \cdot \beta \cdot W_{\max}$ Workpiece mounting coefficient $K$ : Fig.3 Allowable load mass coefficient $\beta$ : Graph 1 Max. allowable moment $W_{\max}$ : Table 2 $\alpha_1 = W / W_a$	$W_a = 1 \times 1 \times 4 = 4$ $K = 1$ $\beta = 1$ $W_{\max} = 4$ $\alpha_1 = \frac{1}{4} = 0.25$
<b>3-2 Load factor of static moment</b>	Calculate static moment $M(N \cdot m)$  $M = W \times 9.8(L_n + A_n) / 1000$ Correction value for center position Distance of moment $A_n$ : Table 3 $M_a = K \cdot \gamma \cdot M_{\max}$ Work mounting coefficient $K$ : Fig.3 Allowable moment coefficient $\gamma$ : Graph 2 Max. allowable moment $M_{\max}$ : Table 4 $\alpha_2 = M / M_a$	<b>Yawing</b> Examine $M_y$ $M_y = 1 \times 9.8(10+30)/1000 = 0.39$ $A_3 = 30$ $M_{ay} = 1 \times 1 \times 15.9 = 15.9$ $M_{ymax} = 15.9$ $K = 1$ $\gamma = 1$ $\alpha_2 = 0.39 / 15.9 = 0.025$ <b>Rolling</b> Examine $M_r$ $M_r = 1 \times 9.8(30+10)/1000 = 0.39$ $A_6 = 10$ $M_{ar} = 15.9$ (Same value as $M_{ay}$ )
<b>3-3 Load rate of kinetic moment</b>	Calculate kinetic moment $M_e(N \cdot m)$  $M_e = \frac{1}{3} \times W_e \times 9.8 \frac{(L_n + A_n)}{1000}$ Calculate allowable kinetic moment $M_{ea}(N \cdot m)$  $M_{ea} = K \cdot \gamma \cdot M_{max}$ Work mounting coefficient $K$ :Fig.3 Allowable moment coefficient $\gamma$ : Graph 2 Max. allowable moment $M_{max}$ :Table 4 $\alpha_3 = M_e / M_{ea}$	<b>Pitching</b> Examine $M_{ep}$ $M_{ep} = \frac{1}{3} \times 16.8 \times 9.8 \times \frac{(30+10)}{1000} = 2.2$ $W_e = 4/100 \times 1 \times 420 = 16.8$ $A_2 = 10$ $M_{ep} = 1 \times 0.7 \times 15.9 = 11.1$ $K = 1$ $\gamma = 0.7$ $M_{pmax} = 15.9$ $\alpha_3 = 2.2 / 11.1 = 0.20$ <b>Yawing</b> Examine $M_{ey}$ $M_{ey} = \frac{1}{3} \times 16.8 \times 9.8 \times \frac{(30+31)}{1000} = 3.3$ $W_e = 168$ $A_4 = 31$ $M_{ey} = 11.1$ (Same value as $M_{ep}$ ) $\alpha_3' = 3.3 / 11.1 = 0.30$
<b>3-4 Sum of load rate</b>	Possible to use if the sum of the load factors does not exceed 1.	$\Sigma \alpha_n = \alpha_1 + \alpha_2 + \alpha_3 + \alpha_3' \leq 1$ $= 0.25 + 0.025 + 0.025 + 0.20 + 0.30 = 0.80 \leq 1$ <p>And it is possible to use.</p>

**Fig.1 Load mass : W (kg)****Fig. 2 Overhang : Ln (mm), correction value of moment center position distance : An (mm)****Fig.3 Work Mounting Coefficient: K****Table 2 Max. allowable static load : Wmax (kg)**

Model	Max. allowable static load
GXS6	0.6
GXS8	1
GXS12	2
GXS16	4
GXS20	6
GXS25	9

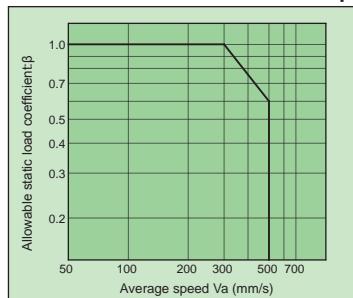
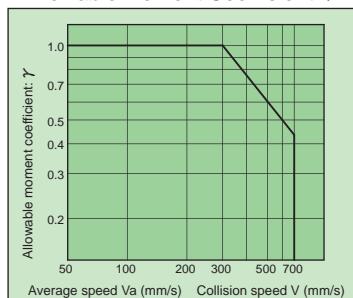
**Table 4 Max. allowable moment: Mmax (N·m)**

Model	Stroke (mm)								
	10	20	30	40	50	75	100	125	150
GXS6	0.7	1.0	1.2	1.2	1.2	—	—	—	—
GXS8	2.0	2.0	2.8	3.6	4.2	4.2	—	—	—
GXS12	4.2	4.2	4.2	5.8	7.0	10.0	10.0	—	—
GXS16	11.3	11.3	11.3	11.3	15.9	25.0	34.1	34.1	—
GXS20	19.4	19.4	19.4	19.4	27.2	35.0	50.5	50.5	50.5
GXS25	30.6	30.6	30.6	30.6	42.8	55.1	67.3	67.3	67.3

**Symbol**

Symbol	Definition	Unit
An(n=1 ~ 6)	Correction value of moment center distance	mm
E	Kinetic energy	J
Ea	Allowable kinetic energy	J
Emax	Max. allowable kinetic energy	J
Ln(n=1 ~ 3)	Overhang	mm
M(Mp,My,Mr)	Static moment (Pitch, Yaw, Roll)	N·m
Ma(Map,May,Mar)	Allowable static moment (Pitch, Yaw, Roll)	N·m
Me(Mep,Mey)	Kinetic moment (Pitch, Yaw)	N·m
Mea(Meap,Meay)	Allowable kinetic moment (Pitch, Yaw)	N·m
Mmax(Mpmax,Mymax, Mrmax)	Max. allowable kinetic moment (Pitch, Yaw, Roll)	N·m
V	Collision speed	mm/s

Symbol	Definition	Unit
Va	Average speed	mm/s
W	Static load	kg
Wa	Allowable static load	kg
We	Load equivalent to collision	kg
Wmax	Max. allowable static load	kg
$\alpha$	Load rate	—
$\beta$	Allowable static load coefficient	—
$\gamma$	Allowable moment coefficient	—
$\delta$	Damper coefficient	—
K	Work mounting coefficient	—

**Graph 1 Allowable static load Coefficient:  $\beta$** **Graph 2 Allowable Moment Coefficient:  $\gamma$** 

● Average speed for static moment  
Collision speed for kinetic moment